

estat policy — Display policy matrix

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Description

`estat policy` displays the estimated policy matrix of the state-space form of a DSGE model.

Quick start

Display the estimated policy matrix

```
estat policy
```

Same as above, but with 90% confidence intervals

```
estat policy, level(90)
```

Menu for estat

Statistics > Postestimation

Syntax

```
estat policy [ , compact post level(#) display_options ]
```

`collect` is allowed; see [\[U\] 11.1.10 Prefix commands](#).

Options

`compact` reports only the coefficient values of the estimated policy matrix and displays these coefficients in matrix form.

`post` causes `estat policy` to behave like a Stata estimation (e-class) command. `estat policy` posts the policy matrix parameters along with the estimated variance–covariance matrix to `e()`, so you can treat the estimated policy matrix as you would results from any other estimation command.

`level(#)` specifies the confidence level, as a percentage, for confidence intervals. The default is `level(95)` or as set by `set level`; see [\[U\] 20.8 Specifying the width of confidence intervals](#).

display_options: `nocl`, `nopvalues`, `cformat(%fmt)`, `pformat(%fmt)`, `sformat(%fmt)`, and `nolstretch`; see [\[R\] Estimation options](#).

Remarks and examples

The policy matrix is part of the state-space form of a DSGE model. It specifies the model's control variables as a function of the model's state variables.

For examples, see [\[DSGE\] Intro 1](#), [\[DSGE\] Intro 3a](#), and [\[DSGE\] Intro 3c](#).

Stored results

`estat policy` stores the following in `r()`:

Matrices

<code>r(policy)</code>	estimated policy matrix
<code>r(b)</code>	estimates
<code>r(V)</code>	variance-covariance matrix of the estimates

If `post` is specified, `estat policy` also stores the following in `e()`:

Macros

<code>e(properties)</code>	<code>b V</code>
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Matrices

<code>e(policy)</code>	estimated policy matrix
<code>e(b)</code>	estimates
<code>e(V)</code>	variance-covariance matrix of the estimates

Methods and formulas

Entries in the policy matrix \mathbf{G} are functions of the structural parameter vector θ . Standard errors for $\hat{\mathbf{G}}$ are calculated using the delta method.

Also see

[\[DSGE\] dsge](#) — Linear dynamic stochastic general equilibrium models

[\[DSGE\] dsge postestimation](#) — Postestimation tools for `dsge`

[\[DSGE\] dsngenl](#) — Nonlinear dynamic stochastic general equilibrium models

[\[DSGE\] dsngenl postestimation](#) — Postestimation tools for `dsngenl`

[\[DSGE\] Intro 1](#) — Introduction to DSGEs

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